SECTION 262923 - VARIABLE-FREQUENCY MOTOR CONTROLLERS

PART 1 - GENERAL

1.1 SUMMARY

A. This Section includes solid-state, pulse-width modulated (PWM), variable frequency controllers (VFCs) for speed control of three-phase, squirrel-cage induction motors.

1.2 SUBMITTALS

A. Product Data: For each type of VFC.

B. Field quality-control test reports.

C. Operation and maintenance data.

D. Load-current and list of settings of adjustable overload relays.

1.3 QUALITY ASSURANCE

A. Electrical Components, Devices, and Accessories: Listed and labeled as defined in NFPA 70, Article 100.

B. Comply with NFPA 70.

C. Product Selection for Restricted Space: Drawings indicate maximum dimensions for VFCs, minimum clearances between VFCs, and adjacent surfaces and other items. Comply with indicated maximum dimensions and clearances.

1.4 PROJECT CONDITIONS

A. Environmental Limitations: Rate equipment for continuous operation, capable of driving full load without derating, under the following conditions, unless otherwise indicated:

1. Ambient Temperature: 0 to 40 deg C.
2. Humidity: Less than 90 percent (noncondensing).
3. Altitude: Not exceeding 3300 feet.

1.5 COORDINATION

A. Coordinate features of VFCs, installed units, and accessory devices with pilot devices and control circuits to which they connect.

B. Coordinate features, accessories, and functions of each VFC and each installed unit with ratings and characteristics of supply circuit, motor, required control sequence, and duty cycle of motor and load.

PART 2 - PRODUCTS

2.1 MANUFACTURERS

A. Available Manufacturers: Subject to compliance with requirements, manufacturers offering products that may be incorporated into the Work include, but are not limited to, the following:

1. ABB Power Distribution, Inc.; ABB Control, Inc. Subsidiary.
2. Baldor Electric Company (Graham).
3. Danfoss Inc.; Danfoss Electronic Drives Div.
4. Eaton Corporation; Cutler-Hammer Products.
5. General Electric Company; GE Industrial Systems.
6. Rockwell Automation; Allen-Bradley Co.; Industrial Control Group.
7. Siemens Energy and Automation; Industrial Products Division.
8. Square D.
9. Toshiba International Corporation.

2.2 VARIABLE FREQUENCY CONTROLLERS

A. Description: NEMA ICS 2, IGBT, PWM, VFC; listed and labeled as a complete unit and arranged to provide variable speed of an NEMA MG 1, Design B, 3-phase induction motor by adjusting output voltage and frequency.

1. Provide unit suitable for operation of premium-efficiency motor as defined by NEMA MG 1.

B. Design and Rating: Match load type such as fans, blowers, and pumps; and type of connection used between motor and load such as direct or through a power-transmission connection.

C. Output Rating: 3-phase; 6 to 60 Hz, with voltage proportional to frequency throughout voltage range.

D. Unit Operating Requirements:

1. Input ac voltage tolerance of 208 V, plus or minus 5 percent.
2. Input frequency tolerance of 50/60 Hz, plus or minus 6 percent.
3. Minimum Efficiency: 96 percent at 60 Hz, full load.
4. Minimum Displacement Primary-Side Power Factor: 96 percent.
5. Overload Capability: 1.1 times the base load current for 60 seconds; 2.0 times the base load current for 3 seconds.
6. Starting Torque: 100 percent of rated torque.
7. Speed Regulation: Plus or minus 1 percent.

E. Isolated control interface to allow controller to follow control signal over an 11:1 speed range.

1. Electrical Signal: 4 to 20 mA at 24 V.
2. Pneumatic Signal: 3 to 15 psig (20 to 104 kPa).

F. Internal Adjustability Capabilities:

1. Minimum Speed: 5 to 25 percent of maximum rpm.
2. Maximum Speed: 80 to 100 percent of maximum rpm.
3. Acceleration: 2 to a minimum of 22 seconds.

4. Deceleration: 2 to a minimum of 22 seconds.
5. Current Limit: 50 to a minimum of 110 percent of maximum rating.

G. Self-Protection and Reliability Features:

1. Input transient protection by means of surge suppressors.
2. Under- and overvoltage trips; inverter overtemperature, overload, and overcurrent trips.
3. Motor Overload Relay: Adjustable and capable of NEMA ICS 2, Class 10 performance.
4. Notch filter to prevent operation of the controller-motor-load combination at a natural frequency of the combination.
5. Instantaneous line-to-line and line-to-ground overcurrent trips.
6. Loss-of-phase protection.
7. Reverse-phase protection.
8. Short-circuit protection.
9. Motor overtemperature fault.

H. Automatic Reset/Restart: Attempts three restarts after controller fault or on return of power after an interruption and before shutting down for manual reset or fault correction. Bidirectional autospeed search shall be capable of starting into rotating loads spinning in either direction and returning motor to set speed in proper direction, without damage to controller, motor, or load.

I. Power-Interruption Protection: To prevent motor from re-energizing after a power interruption until motor has stopped.

J. Torque Boost: Automatically varies starting and continuous torque to at least 1.5 times the minimum torque to ensure high-starting torque and increased torque at slow speeds.

K. Motor Temperature Compensation at Slow Speeds: Adjustable current fall-back based on output frequency for temperature protection of self-cooled, fan-ventilated motors at slow speeds.

L. Status Lights: Door-mounted LED indicators shall indicate the following conditions:

1. Power on.
2. Run.
3. Overvoltage.
4. Line fault.
5. Overcurrent.
6. External fault.

M. Panel-Mounted Operator Station: Start-stop and auto-manual selector switches with manual speed control potentiometer and elapsed time meter.

N. Indicating Devices: Meters or digital readout devices and selector switch, mounted flush in controller door and connected to indicate the following controller parameters:

1. Output frequency (Hz).
2. Motor speed (rpm).
3. Motor status (running, stop, fault).
4. Motor current (amperes).
5. Motor torque (percent).
6. Fault or alarming status (code).
7. PID feedback signal (percent).
8. DC-link voltage (VDC).
9. Set-point frequency (Hz).

10. Motor output voltage (V).

O. Control Signal Interface:

1. Electric Input Signal Interface: A minimum of 2 analog inputs (0 to 10 V or 0/4-20 mA) and 6 programmable digital inputs.
2. Pneumatic Input Signal Interface: 3 to 15 psig.
3. Remote Signal Inputs: Capability to accept any of the following speed-setting input signals from the BMS or other control systems:

   a. 0 to 10-V dc.
   b. 0-20 or 4-20 mA.
   c. Potentiometer using up/down digital inputs.
   d. Fixed frequencies using digital inputs.
   e. RS485.
   f. Keypad display for local hand operation.

4. Output Signal Interface:

   a. A minimum of 1 analog output signal (0/4-20 mA), which can be programmed to any of the following:

      1) Output frequency (Hz).
      2) Output current (load).
      3) DC-link voltage (VDC).
      4) Motor torque (percent).
      5) Motor speed (rpm).
      6) Set-point frequency (Hz).

5. Remote Indication Interface: A minimum of 2 dry circuit relay outputs (120-V ac, 1 A) for remote indication of the following:

   a. Motor running.
   b. Set-point speed reached.
   c. Fault and warning indication (overtemperature or overcurrent).
   d. PID high- or low-speed limits reached.

P. Communications: Provide an RS485 interface allowing VFC to be used with an external system within a multidrop LAN configuration. Interface shall allow all parameter settings of VFC to be programmed via BMS control. Provide capability for VFC to retain these settings within the nonvolatile memory.

Q. Manual Bypass: Magnetic contactor arranged to safely transfer motor between controller output and bypass controller circuit when motor is at zero speed. Controller-off-bypass selector switch sets mode, and indicator lights give indication of mode selected. Unit shall be capable of stable operation (starting, stopping, and running), with motor completely disconnected from controller (no load).

R. Bypass Controller: NEMA ICS 2, full-voltage, nonreversing enclosed controller with across-the-line starting capability in manual-bypass mode. Provide motor overload protection under both modes of operation with control logic that allows common start-stop capability in either mode.

S. Integral Disconnecting Means: NEMA AB 1, instantaneous-trip circuit breaker with lockable handle.

T. Isolating Switch: Non-load-break switch arranged to isolate VFC and permit safe troubleshooting and testing, both energized and de-energized, while motor is operating in bypass mode.

U. Remote Indicating Circuit Terminals: Mode selection, controller status, and controller fault.

2.3 ENCLOSURES

A. Enclosure Type: NEMA Type 4X (outdoor); NEMA Type 12 (indoor).

2.4 ACCESSORIES

A. Devices shall be factory installed in controller enclosure, unless otherwise indicated.

B. Push-Button Stations, Pilot Lights, and Selector Switches: NEMA ICS 2, heavy-duty type.

C. Stop and Lockout Push-Button Station: Momentary-break, push-button station with a factory-applied hasp arranged so padlock can be used to lock push button in depressed position with control circuit open.

D. Control Relays: Auxiliary and adjustable time-delay relays.

E. Standard Displays:

1. Output frequency (Hz).
2. Set-point frequency (Hz).
3. Motor current (amperes).
4. DC-link voltage (VDC).
5. Motor torque (percent).
6. Motor speed (rpm).
7. Motor output voltage (V).

F. Historical Logging Information and Displays:

1. Real-time clock with current time and date.
2. Running log of total power versus time.
3. Total run time.
4. Fault log, maintaining last four faults with time and date stamp for each.

G. Current-Sensing, Phase-Failure Relays for Bypass Controller: Solid-state sensing circuit with isolated output contacts for hard-wired connection; arranged to operate on phase failure, phase reversal, current unbalance of from 30 to 40 percent, or loss of supply voltage; with adjustable response delay.

2.5 FACTORY FINISHES

A. Finish: Manufacturer's standard paint applied to VFCs before shipping.

PART 3 - EXECUTION

3.1 APPLICATIONS

A. Select features of each VFC to coordinate with ratings and characteristics of supply circuit and motor; required control sequence; and duty cycle of motor, controller, and load.

B. Select horsepower rating of controllers to suit motor controlled.

3.2 INSTALLATION

A. Comply with mounting and anchoring requirements specified in Division 26 Section "Hangers and Supports for Electrical Systems."

3.3 IDENTIFICATION

A. Identify VFCs, components, and control wiring according to Division 26 Section "Identification for Electrical Systems."

B. Operating Instructions: Frame printed operating instructions for VFCs, including control sequences and emergency procedures. Fabricate frame of finished metal, and cover instructions with clear acrylic plastic. Mount on front of VFC units.

3.4 CONTROL WIRING INSTALLATION

A. Install wiring between VFCs and remote devices according to Division 26 Section "Low-Voltage Electrical Power Conductors and Cables."

B. Bundle, train, and support wiring in enclosures.

C. Connect hand-off-automatic switch and other automatic-control devices where applicable.

1. Connect selector switches to bypass only manual- and automatic-control devices that have no safety functions when switch is in hand position.
2. Connect selector switches with control circuit in both hand and automatic positions for safety-type control devices such as low- and high-pressure cutouts, high-temperature cutouts, and motor overload protectors.

3.5 FIELD QUALITY CONTROL

A. Prepare for acceptance tests as follows:

1. Test insulation resistance for each enclosed controller element, bus, component, connecting supply, feeder, and control circuit.
2. Test continuity of each circuit.

B. Manufacturer's Field Service: Engage a factory-authorized service representative to perform the following:

1. Inspect controllers, wiring, components, connections, and equipment installation.
2. Assist in field testing of equipment including pretesting and adjusting of solid-state controllers.
3. Report results in writing.

C. Perform the following field tests and inspections and prepare test reports:

1. Perform each electrical test and visual and mechanical inspection, except optional tests, stated in NETA ATS. Certify compliance with test parameters.
2. Correct malfunctioning units on-site, where possible, and retest to demonstrate compliance; otherwise, replace with new units and retest.

3.6 ADJUSTING

A. Set field-adjustable circuit-breaker trip ranges.

3.7 DEMONSTRATION

A. Train Owner's maintenance personnel to adjust, operate, and maintain controllers.

END OF SECTION 262923